



Voltage Type Single-axis Inclinometer

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General Description

HVS118T is a single axis inclinometer with analog voltage output, the user simply collecting the inclinometer voltage value then can calculate the inclination of the current object. Built-in (MEMS) micro solid pendulum into angle changes by measuring the static gravity field changes, changes in mode output voltage (0-5V). - ainly used to measure the inclination of the object with respect to the horizontal plane.simple installation. high-precision, small size, strong resistance to external electromagnetic interference ability, the ability to withstand shock and vibration. It is the ideal choice for industrial equipment, platform measuring attitude!

Specifications

Accuracy: 0.01° Resolution: 0.01°

Measuring axis: Y-axis

Power supply voltage range: 9-35v Anti-vibration performance: >2000g

Store temperature: -55°C~+100°C

Zero temperature drift (-40 ° C ~ 85 ° C): ± 0.005 °

Protection rating: IP67 Measuring range: ±90°

Output signal:voltage output

Wide temperature working: -40°C ~ +85°C

Applications

1: Industrial automatic leveling

3: Solar automatic tracking

5: Lifting angle control of cranes

7: Measuring and mapping instruments

2: Medical equipment

4: Tower tilt monitoring

6: Structural deformation monitoring

8: Military equipment automation



Electrical parameters

Parameters	conditions	Min	Standard	Max	Unit
power supply		5	12 24	36	V
Working current		15	30	40	mA
Working temperature		-40		+85	°C
Store temperature		-55		+100	°C

Technical Data

Parameters	conditions	HVS118T-10	HVS118T-30	HVS118T-60	HVS118T-90
Measuring rang		±10°	±30°	±60°	±90°
Measuring axis		Υ	Υ	Y	Υ
Resolution		0.01°	0.01°	0.01°	0.01°
Zero temperat- ure coefficient	-40°C~85°C	0.005°/°C	0.005°/°C	0.005°/°C	0.005°/°C
Absolute accuracy		0.01°	0.015°	0.02°	0.03°
Zero Position	0° Output	2.5V	2.5V	2.5V	2.5V
Power on time		<3S	<3S	<38	<3S
Output frequency	5-100HZ	Optional	Optional	Optional	Optional
Baud rate	2400-115200	Optional	Optional	Optional	Optional
Shockproof	2000g.0.5ms、3Times/Axis(half sinusoid)				
Average no reason Obstacle time MTBF	≥800000hours/times				
Insulation resistance	≥100MΩ				
Output signal	0~4.5V、0~5V、0~10V				
Weight	100g(without cable)				

This Technical data only list \pm 10 °, \pm 30 °, \pm 60 °, \pm 90 ° series for reference, other measuring range please refer to the adjacent parameters.

Key words

Resolution: Refers to the sensor in measuring range to detect and identify the smallest changed value.

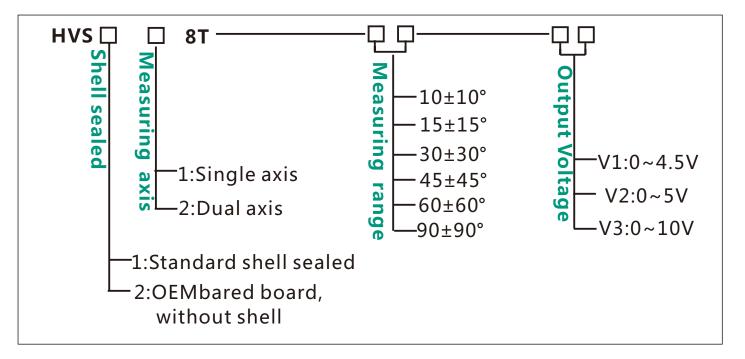
Absolute accuracy: Refers to in the normal temperature circumstances, the sensor absolute linearity, repeatability, hysteresis, zero deviation, and transverse error comprehensive error.

Response time: Refers to the sensor in an angle change, the sensoroutput value reached the standardtime required.

Mechanical Parameters

Connectors	1.2m lead cable (customized)		
Protection glass	IP67		
Enclosure material	Aluminum Oxide		
Installation	4*M4 screws		

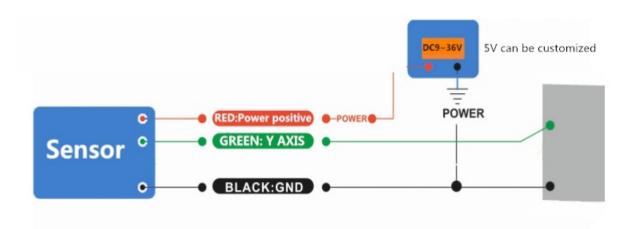
Ordering information



E.g : HVS 11 8 T -10-V1 : standard/single axis/ $\pm 10^\circ$ Measuring range / $0 \sim 4.5$ V output Voltage

Electrical Connection

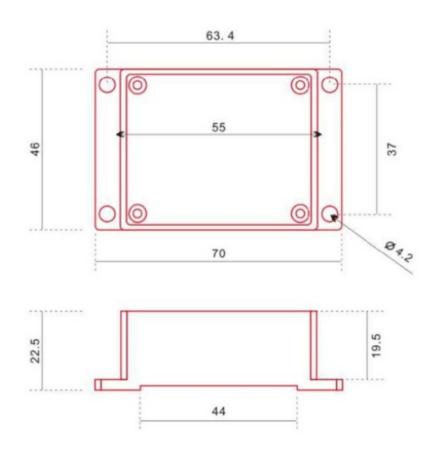
Line	RED	BLACK	GREEN
color function	DC 9~36V	GND Power Negative	Y axis



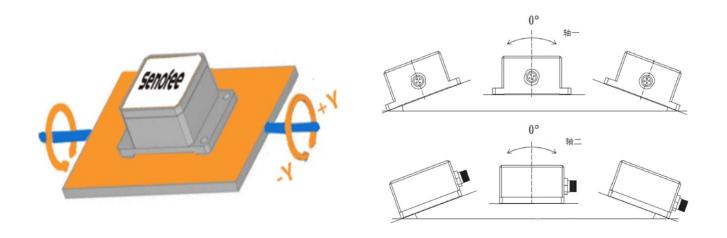
Working Principle

Adopt the European import of core control unit, using the capacitive micro pendulum principle and the earth gravity principle, when the the inclination unit is tilted, the Earth's gravity on the corresponding pendulum will produce a component of gravity, corresponding to the electric capacity will change, by enlarge the amount of electric capacity, filtering and after conversion then get the inclination.

Product size chart



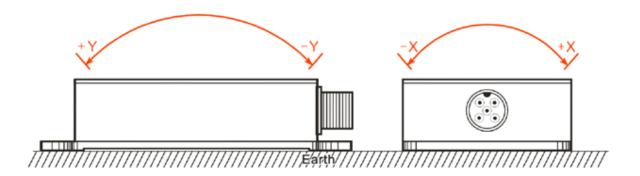
Measuring direction



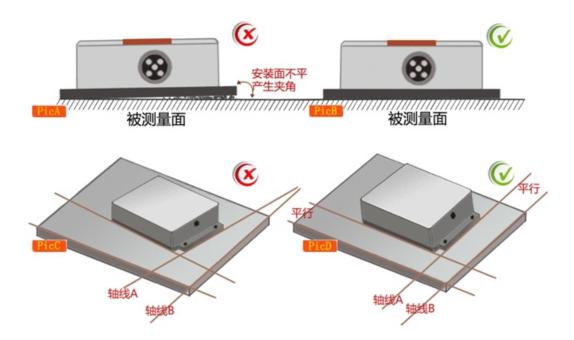
Production installation notes:

Please follow the correct way to install tilt sensor, incorrect installation can cause measurement errors, with particular attention to the "surface", "line": :

- 1) The Sensor mounting surface and the measured surface must be fixed closely, smoothly, stability, if mounting surface uneven likely to cause the sensor to measure the angle error. See Figure Pic.AB
- 2) The sensor axis and the measured axis must be parallel ,the two axes do not produce the angle as much as possible. See Figure Pic.CD :



The axis of the sensor must be parallel to the axis to be measured, and the two axes should not be angled as much as possible.



The mounting surface of the sensor must be tight, flat and stable when it is fixed to the surface to be measured.

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